

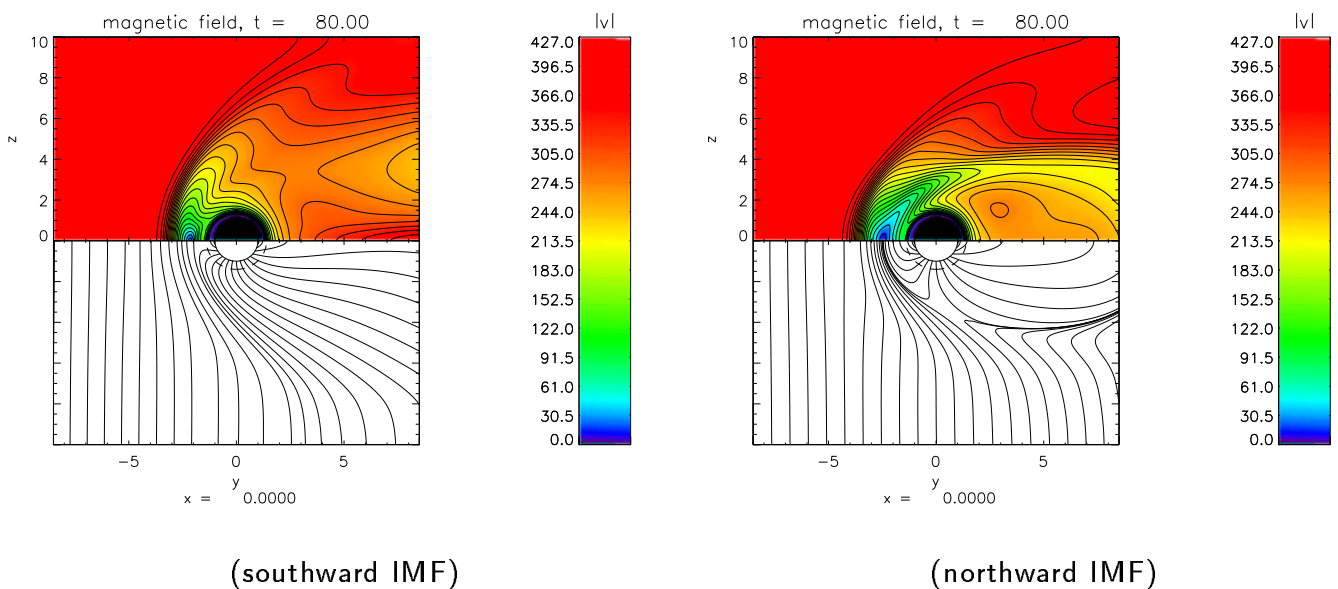
Resistive MHD simulations of the interaction of the solar wind with magnetized planets

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- Example: Interaction of the solar wind with Mercury:
 - colour: flow velocity of the solar wind in km/s
 - field lines: magnetic field (a superposition of the interplanetary magnetic field (IMF) and Mercury's dipole field)



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Basic equations of resistive MHD with mass source:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= -\vec{\nabla} \cdot (\rho \vec{v}) + \dot{\rho} \\ \frac{\partial \rho \vec{v}}{\partial t} &= -\vec{\nabla} \cdot (\rho \vec{v} \vec{v}) - \vec{\nabla} P + \vec{j} \times \vec{B} + \dot{\rho} \vec{v}_q \\ \frac{\partial \vec{B}}{\partial t} &= -\vec{\nabla} \times \vec{E} = \vec{\nabla} \times (\vec{v} \times \vec{B} - \eta \vec{j}) \\ \frac{\partial \rho \varepsilon}{\partial t} &= -\vec{\nabla} \cdot (\rho \varepsilon \vec{v}) - P \vec{\nabla} \cdot \vec{v} + \eta \vec{j}^2 + \frac{\dot{\rho}}{\rho} P\end{aligned}$$

- Maxwell equations:

$$\begin{aligned}\rightarrow \vec{j} \times \vec{B} &= \frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) \times \vec{B} = \frac{1}{\mu_0} \left(\vec{\nabla} \cdot (\vec{B} \vec{B}) + (\vec{\nabla} \cdot \vec{B}) \vec{B} - \frac{1}{2} \vec{\nabla} (\vec{B} \cdot \vec{B}) \right) \\ \rightarrow \frac{\partial \rho \vec{v}}{\partial t} &= -\vec{\nabla} \cdot \left((P + \vec{B}^2 / 2\mu_0) \mathbf{1} + (\rho \vec{v} \vec{v} - (\vec{B} \vec{B}) / \mu_0) \right)\end{aligned}$$

- Ideal gas: $\rho \varepsilon = 1/(\gamma - 1)P \rightarrow$ equation for P alone:

$$\frac{1}{\gamma - 1} \frac{\partial P}{\partial t} = -\frac{1}{\gamma - 1} \vec{\nabla} \cdot (P \vec{v}) - P \vec{\nabla} \cdot \vec{v} + \eta \vec{j}^2 + \frac{\dot{\rho}}{\rho} P$$

- The resistivity can depend on the current density (anomalous resistivity)
- Normalization leads to $P \rightarrow P/2$ and $\eta \rightarrow \eta/S$ (Lundquist number)
- Further simplification by introducing the function $u := (P/2)^{\frac{1}{\gamma}}$

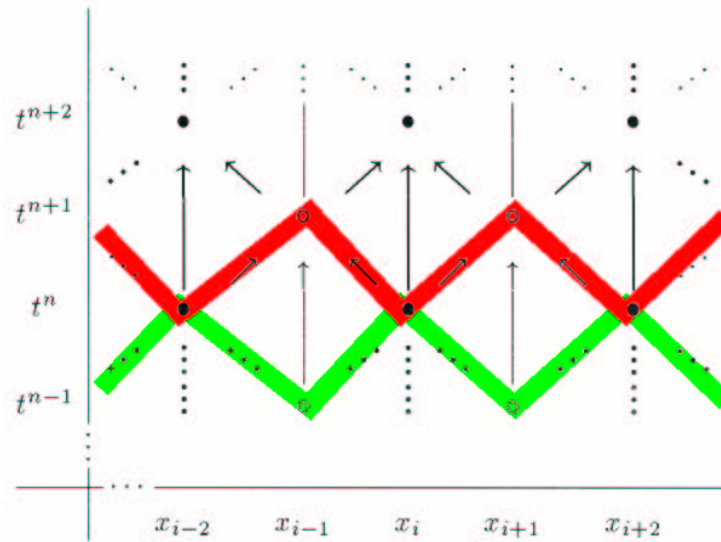
\rightarrow Normalized equations (with $\vec{s} := \rho \vec{v}$):

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= -\vec{\nabla} \cdot \vec{s} + \dot{\rho} \\ \frac{\partial \vec{s}}{\partial t} &= -\vec{\nabla} \cdot \left(\vec{s} \vec{v} + u^\gamma \mathbf{1} \right) + \vec{j} \times \vec{B} + \dot{\rho} \vec{v}_q \\ &= -\vec{\nabla} \cdot \left(\vec{s} \vec{v} - \vec{B} \vec{B} + (u^\gamma + \frac{1}{2} \vec{B}^2) \mathbf{1} \right) + \dot{\rho} \vec{v}_q \\ \frac{\partial \vec{B}}{\partial t} &= \vec{\nabla} \times (\vec{v} \times \vec{B}) + \frac{1}{S} \left(\eta \Delta \vec{B} - \vec{\nabla} \eta \times \vec{j} \right) \\ \frac{\partial u}{\partial t} &= -\vec{\nabla} \cdot (u \vec{v}) + \frac{\gamma - 1}{\gamma} u^{1-\gamma} \left(\frac{\dot{\rho}}{\rho} u^\gamma + \eta \vec{j}^2 \right)\end{aligned}$$

The numerical method:

- The balance equations are hyperbolic → **Leapfrog** scheme
- The induction equation is parabolic → **Dufort-Frankel** scheme
- One-dimensional example:
 - time steps: $t_n := t_0 + n\Delta t$
 - grid: $x_i := x_{min} + i\Delta x$, with: $x_1 = x_{min}, x_N = x_{max}$
- Both schemes are of second order in space and time

→ The numerical grid is divided into two staggered subgrids:



- There are only grid points with $n+i = \text{even}^*)$:
 - grid "◦": $n = \text{odd}, i = \text{odd}$
 - grid "•": $n = \text{even}, i = \text{even}$

→ **no grid points with $n+i = \text{odd} : n = \text{odd/even}, i = \text{even/odd!}$**

 - in the code: the time is not labeled, but included implicitly, e.g.
 - ① **index = i → t=n (•), index=i±1 → t=n-1 (◦)** (=grid before step 1[†])
 - ② **index = i → t=n (•), index=i±1 → t=n+1 (◦)** (=grid after step 1)
- All grid points are known at $t = 0$ (labeled then as grid "•")
 - a half integration step initializes grid "◦"

^{*)} or odd, depending on the definition of the grid

^{†)} cf. next page

The integration schemes:

- Abbreviations: $u_i^n := u(x=x_i, t=t_n)$, $F_i^n := F(u_i^n)$
-

- **The leapfrog scheme:**

- simplest example:

$$\frac{\partial u}{\partial t} = -\frac{\partial F(u)}{\partial x}$$

- step 1 (computes grid ◦):

$$u_{i+1}^{n+1} = u_{i+1}^{n-1} - \frac{\Delta t}{\Delta x} (F_{i+2}^n - F_i^n) \quad \text{and} \quad u_{i-1}^{n+1} = u_{i-1}^{n-1} - \frac{\Delta t}{\Delta x} (F_i^n - F_{i-2}^n)$$

- step 2 (computes grid ●):

$$u_i^{n+2} = u_i^n - \frac{\Delta t}{\Delta x} (F_{i+1}^{n+1} - F_{i-1}^{n+1})$$

- **The Dufort-Frankel scheme:**

- simplest example:

$$\frac{\partial u}{\partial t} = \kappa \frac{\partial^2 u}{\partial x^2}$$

- the leapfrog scheme is unstable in this case

(and the point u_{i+1}^n does not exist; in the code: u_{i+1} stands for u_{i+1}^{n-1})

→ time average of the Laplace term:

- scheme demonstrated here only for the first step:

$$u_{i+1}^{n+1} = u_{i+1}^{n-1} + \kappa \frac{2\Delta t}{\Delta x^2} \left(u_{i+2}^n - \underbrace{(u_{i+1}^{n+1} + u_{i+1}^{n-1})}_{\text{average}} + u_i^n \right)$$

→ semi-implicit scheme, equation can be solved for u_{i+1}^{n+1} :

$$\rightarrow u_{i+1}^{n+1} = \left(u_{i+1}^{n-1} + \kappa \frac{2\Delta t}{\Delta x^2} (u_{i+2}^n - u_{i+1}^{n-1} + u_i^n) \right) / \left(1 + \kappa \frac{2\Delta t}{\Delta x^2} \right)$$

Numerical realization of the solar wind interaction with a planet:

- Coordinates:
 - \hat{y} flow direction, \hat{z} main direction of the IMF (S→N), $\hat{x} = \hat{y} \times \hat{z}$
 - the planet (with radius R) is located at the origin (only for $t > 0$, see below)
- Initial state:
 - all quantities are homogeneous, $\vec{v} = v_{SW}\hat{y}$
 - the planet does not occur in the initial state, but ...
- ... is introduced by a time-dependent function f which slows down the plasma:

$$f(x, y, z, t) = \kappa \left(\left(\frac{t}{\tau} \right)^2 \right) \cos^2 \left(\frac{\pi}{2} \kappa(\tilde{r}) \right), \text{ with: } \kappa(x) := \max(\min(x, 1), 0),$$

- $\tilde{r} := (r - R)/\Delta r$ and $r := \sqrt{x^2 + y^2 + z^2}$
 - Δr is a "smoothness parameter" (typical value: $\Delta r = 0.4$)
-

- The source terms:
 - mass loading takes place within a sphere of radius $R_A > R$ (the "atmosphere")
 - expression: $\dot{\rho} = Q_0 \exp\left(-\frac{(r' - R)}{(R_A - R) \ln(\varepsilon)}\right)$, with $r' = \max(r, R)$
 → $\dot{\rho}$ has the value $\dot{\rho} = Q_0 \varepsilon$ at $r = R_A$
 - velocity: \vec{v}_q is the velocity of the newly generated particles:
 e.g. $\vec{v}_q = \vec{v}$ for pickup ions or $\vec{v}_q = v_0 \hat{r}$ for a plasma source (\hat{r} : radius vector)
-

- Numerical realization of an intrinsic dipole field:
 - e.g. for magnetic moment in z -direction: $\vec{B} = B_0(3xz, 3yz, 2z^2 - x^2 - y^2)/r^5$
 - problems: field diverges for $r \rightarrow 0$, steep gradient
 → define a radius $r_0 < R$ (typical value: $r_0 = 0.6R$)
 → replace $1/r^5$ by $g(r) = (1/r_0^5)((n+5)(r/r_0)^{n-1} - (n+4)(r/r_0)^n)$ (e.g. $n = 8$)
 → keep the magnetic field fixed for $r \leq r_0$ (do not integrate)
 → subtract quantities vanishing analytically in the initial state: $\vec{j} \rightarrow \vec{j} - \vec{j}_{initial}$,
 same for $\Delta \vec{B}$ (if necessary also for the rhs. of the momentum balance eqn.)

Boundary conditions in upstream direction

- all quantities are kept fixed (with a smooth transition to the interior)

Method for the other boundaries: Consider lower (left) boundary in 1D:

- x_1 : numerical boundary (for derivatives), x_2 : physical boundary

→ x_1 and x_2 belong to different grids → compute u_1 with u_3 and u_5 :

$$u_1 = ku_3 - au'_3(x_3 - x_1)$$

→ special cases: $a = 0$ and $k = (-)1$ (anti)symmetry, $a > 0$: extrapolation

- extrapolation: need "wrong" values u_2 and u_4 for the computation of u'_3

→ use average of u'_2 and u'_4 instead, where u'_2 contains the (unknown) value u_1 :

$$\begin{aligned} \rightarrow u_1 &= ku_3 - a \left(\frac{x_4 - x_3}{x_4 - x_2} u'_2 + \frac{x_3 - x_2}{x_4 - x_2} u'_4 \right) (x_3 - x_1) \\ &= ku_3 - a \left(\frac{x_4 - x_3}{x_4 - x_2} \frac{u_3 - u_1}{x_3 - x_1} + \frac{x_3 - x_2}{x_4 - x_2} \frac{u_5 - u_3}{x_5 - x_3} \right) (x_3 - x_1) \end{aligned}$$

→ semi-implicit, for "exact" extrapolation ($a = 1, k = 1$) this leads to:

$$u_1 = \frac{x_5 - x_3 + x_3 - x_1}{x_5 - x_3} u_3 - \frac{x_3 - x_1}{x_5 - x_3} u_5 \rightarrow \text{this means: resulting } u'_2 = u'_4!$$

→ problems when perturbations move towards the boundary (→ oscillations)

New method: extrapolate u'_2 and make use of the fact that the derivatives

(but not necessarily the values) for both grids are continuous:

$$u'_2 = u'_3 - (x_3 - x_2) \left(\frac{u'_4 - u'_3}{x_4 - x_3} \right)$$

- introduce a "damping factor" $0 \leq \alpha \leq 1$ (to avoid overshooting) and write:

$$u_1 = u_3 - \alpha u'_2 (x_3 - x_1) \quad (u'_2 \text{ is now known and doesn't contain } u_1)$$

→ results in an expression $u_1 = C_1 u_2 + C_2 u_3 + C_3 u_4 + C_4 u_5$ with:

$$C_2 = \alpha \frac{x_3 - x_1}{x_4 - x_3}, \quad C_3 = 1 - C_2 \alpha \frac{x_3 - x_2}{x_5 - x_3}, \quad C_4 = -C_2, \quad C_5 = 1 - C_3$$

→ couples the grids (helps against the odd-even instability)

- if perturbations propagating to the boundary still cause problems, u_2 can be computed with the same method (with $u_3 - u_6$) before u_1 is computed

DENISIS (Dust Electron Neutral Ion Self-consistent Integration Scheme):

- 4-fluid model, where the dust can be replaced by a 2^{nd} ion species
- Basic equations for each species α ($\alpha = e, i, n, \text{ or } d$):

$$\begin{aligned}
 \frac{\partial \rho_\alpha}{\partial t} &= -\vec{\nabla} \cdot (\rho_\alpha \vec{v}_\alpha) + Q_\alpha^C \\
 \frac{\partial \rho_\alpha \vec{v}_\alpha}{\partial t} &= -\vec{\nabla} \cdot (\rho_\alpha \vec{v}_\alpha \vec{v}_\alpha) - \vec{\nabla} P_\alpha + q_\alpha (\vec{E} + \vec{v}_\alpha \times \vec{B}) + \vec{Q}_\alpha^S + \vec{F}_\alpha^S \\
 \frac{\partial \vec{B}}{\partial t} &= -\vec{\nabla} \times \vec{E} \\
 \frac{1}{\gamma_\alpha - 1} \frac{\partial P_\alpha}{\partial t} &= -\frac{1}{\gamma_\alpha - 1} \vec{\nabla} \cdot (P_\alpha \vec{v}_\alpha) - P_\alpha \vec{\nabla} \cdot \vec{v}_\alpha + Q_\alpha^E + F_\alpha^E
 \end{aligned}$$

- Source terms: Q : interaction between the species, F : external sources
- Charge $q_\alpha = \sigma_\alpha e z_\alpha$ where $\sigma_{e/d} = -1$, $\sigma_i = +1$ (z_α : charge number)
- Basic assumptions (only necessary for the electrons):
 - quasineutrality $\rightarrow \rho_e = m_e (z_i \rho_i / m_i - z_d \rho_d / m_d)$
 - electrons inertialess: $d(\rho_e \vec{v}_e) / dt = 0 \rightarrow$ equation for the electric field
 \rightarrow the electron velocity is computed from: $\vec{\nabla} \times \vec{B} = \mu_0 \vec{j} = \mu_0 \sum_\alpha q_\alpha n_\alpha \vec{v}_\alpha$

- Numerical realization of the source terms (contain "wrong" grid points u_{i+1}^n):

$$\frac{\partial u}{\partial t} = -\frac{\partial F(u)}{\partial x} + \alpha u$$

\rightarrow new method with 3 steps:

- ① replace u_{i+1}^t by its spatial average and perform a half step:

$$u_{i+1}^n = u_{i+1}^{n-1} - \frac{\Delta t}{2\Delta x} (u_{i+2}^n - u_i^n) + \frac{\alpha \Delta t}{2} (u_{i+2}^n + u_i^n)$$

- ② substitute the averaged source term by the newly computed one:

$$\tilde{u}_{i+1}^n = u_{i+1}^n - \alpha \Delta t \left(\frac{1}{2} (u_{i+2}^n + u_i^n) + u_{i+1}^n \right)$$

- ③ perform the second half of the time step with the new source term:

$$u_{i+1}^{n+1} = \tilde{u}_{i+1}^n - \frac{\Delta t}{2\Delta x} (u_{i+2}^n - u_i^n) + \alpha \Delta t u_{i+1}^n$$

The Dust-MHD equations:

- Continuity equations:

$$\begin{aligned}\rho_e &= m_e(z_i\rho_i/m_i - z_d\rho_d/m_d) \quad (\text{QN}) \\ \frac{\partial\rho_i}{\partial t} &= \vec{\nabla} \cdot \rho_i\vec{v}_i + \nu\rho_n - \xi\rho_i\rho_e \\ \frac{\partial\rho_d}{\partial t} &= \vec{\nabla} \cdot \rho_d\vec{v}_d \\ \frac{\partial\rho_n}{\partial t} &= \vec{\nabla} \cdot \rho_n\vec{v}_n - \nu\rho_n + \xi\rho_i\rho_e\end{aligned}$$

(ν : ionisation frequency, ξ : recombination frequency)

- Momentum balance equations:

- $d(\rho_e\vec{v}_e)/dt = 0$ gives the electric field:

$$\vec{E} = -\frac{m_e}{e\rho_e}\vec{\nabla}P_e - \vec{v}_e \times \vec{B} + \frac{m_e}{e\rho_e}(\vec{F}_e^S + \vec{Q}_e^S)$$

- \vec{v}_e follows from the current density:

$$\vec{v}_e = \frac{m_e\rho_i}{m_i\rho_e}z_i\vec{v}_i - \frac{m_e\rho_d}{m_d\rho_e}z_d\vec{v}_d - \frac{m_e}{\mu_0e\rho_e}\vec{\nabla} \times \vec{B}$$

- equations for the other species:

$$\begin{aligned}\frac{\partial\rho_i\vec{v}_i}{\partial t} &= -\vec{\nabla} \cdot (\rho_i\vec{v}_i\vec{v}_i) - \vec{\nabla}P_i + q_i(\vec{E} + \vec{v}_i \times \vec{B}) + \rho_i\vec{g} + \vec{\Gamma}_i + \nu\rho_i\vec{v}_n - \xi\rho_i\rho_e\vec{v}_i \\ &\quad - \nu_{ei}\rho_e(\vec{v}_e - \vec{v}_i) - \nu_{ni}\rho_n(\vec{v}_n - \vec{v}_i) - \nu_{di}\rho_d(\vec{v}_d - \vec{v}_i) \\ \frac{\partial\rho_n\vec{v}_n}{\partial t} &= -\vec{\nabla} \cdot (\rho_n\vec{v}_n\vec{v}_n) - \vec{\nabla}P_n + \rho_n\vec{g} + \vec{\Gamma}_n - \nu\rho_i\vec{v}_n + \xi\rho_i\rho_e\vec{v}_i \\ &\quad - \nu_{en}\rho_e(\vec{v}_e - \vec{v}_n) - \nu_{in}\rho_i(\vec{v}_i - \vec{v}_n) - \nu_{dn}\rho_d(\vec{v}_d - \vec{v}_n) \\ \frac{\partial\rho_d\vec{v}_d}{\partial t} &= -\vec{\nabla} \cdot (\rho_d\vec{v}_d\vec{v}_d) - \vec{\nabla}P_d + q_d(\vec{E} + \vec{v}_d \times \vec{B}) + \rho_d\vec{g} + \vec{\Gamma}_d \\ &\quad - \nu_{ed}\rho_e(\vec{v}_e - \vec{v}_d) - \nu_{id}\rho_i(\vec{v}_i - \vec{v}_d) - \nu_{nd}\rho_n(\vec{v}_n - \vec{v}_d)\end{aligned}$$

(\vec{g} : external gravitation, $\vec{\Gamma}_\alpha$: radiation pressure, $\nu_{\alpha\beta}$: collision frequency,

with symmetry condition: $\rho_\alpha\nu_{\alpha\beta} = \rho_\beta\nu_{\beta\alpha}$)

- Induction equation:

$$\begin{aligned} \frac{\partial \vec{B}}{\partial t} = & \vec{\nabla} \times (\vec{v}_e \times \vec{B}) + \frac{m_e}{e} \frac{1}{\rho_e^2} \vec{\nabla} P_e \times \vec{\nabla} \rho_e - \frac{m_e}{e} \vec{\nabla} \times \left(\frac{1}{\rho_e} \vec{\Gamma}_e \right) \\ & + \frac{m_e}{e} \vec{\nabla} \times \left(\frac{1}{\rho_e} (\nu_{ie} \rho_i (\vec{v}_i - \vec{v}_e) + \nu_{ne} \rho_n (\vec{v}_n - \vec{v}_e) + \nu_{de} \rho_d (\vec{v}_d - \vec{v}_e)) \right) \end{aligned}$$

→ with \vec{v}_e inserted:

$$\begin{aligned} \frac{\partial \vec{B}}{\partial t} = & \frac{m_e \rho_i}{m_i \rho_e} z_i \vec{\nabla} \times (\vec{v}_i \times \vec{B}) - \frac{m_e \rho_d}{m_d \rho_e} z_d \vec{\nabla} \times (\vec{v}_d \times \vec{B}) \\ & - \frac{m_e}{\mu_0 e \rho_e} \vec{\nabla} \times ((\vec{\nabla} \times \vec{B}) \times \vec{B}) + \frac{m_e}{e} \frac{1}{\rho_e^2} \vec{\nabla} P_e \times \vec{\nabla} \rho_e - \frac{m_e}{e} \vec{\nabla} \times \left(\frac{1}{\rho_e} \vec{\Gamma}_e \right) \\ & + \frac{m_e}{e} \vec{\nabla} \times \left(\frac{1}{\rho_e} \left(\nu_{ie} \rho_i \left(\left(1 - \frac{m_e \rho_i}{m_i \rho_e} z_i \right) \vec{v}_i + \frac{m_e \rho_d}{m_d \rho_e} z_d \vec{v}_d + \frac{m_e}{\mu_0 e \rho_e} \vec{\nabla} \times \vec{B} \right) \right. \right. \\ & \quad \left. \left. + \nu_{ne} \rho_n \left(\vec{v}_n - \frac{m_e \rho_i}{m_i \rho_e} z_i \vec{v}_i + \frac{m_e \rho_d}{m_d \rho_e} z_d \vec{v}_d + \frac{m_e}{\mu_0 e \rho_e} \vec{\nabla} \times \vec{B} \right) \right. \right. \\ & \quad \left. \left. + \nu_{de} \rho_d \left(\left(1 + \frac{m_e \rho_d}{m_d \rho_e} z_d \right) \vec{v}_d - \frac{m_e \rho_i}{m_i \rho_e} z_i \vec{v}_i + \frac{m_e}{\mu_0 e \rho_e} \vec{\nabla} \times \vec{B} \right) \right) \right) \end{aligned}$$

→ includes the Hall term

→ a magnetic field may be generated just by collisions, without any seed field

- Conservation laws:

○ **Mass:** $M = \sum_{\alpha} \int \rho_{\alpha} d^3 r = 0 \rightarrow \boxed{\sum_{\alpha} Q_{\alpha}^C = 0}$

○ **Momentum:** $\vec{p} = \int (\sum_{\alpha} \rho_{\alpha} \vec{v}_{\alpha} + \vec{\nabla} \cdot \mathbf{M} - (\sigma_{el} \vec{E} + \vec{j} \times \vec{B})) d^3 r = 0$

($\mathbf{M} = \epsilon_0 \vec{E} \vec{E} + (1/\mu_0) \vec{B} \vec{B} - \frac{1}{2} (\epsilon_0 \vec{E}^2 + ((1/\mu_0) \vec{B}^2) \mathbf{1}$: Maxwellian stress tensor)

→ $\boxed{\sum_{\alpha} \vec{Q}_{\alpha}^S = 0}$

○ **Energy:** $\mathcal{E} = \int (\sum_{\alpha} (\rho_{\alpha} \epsilon_{\alpha} + \frac{1}{2} \rho_{\alpha} \vec{v}_{\alpha}^2) + \epsilon_0 \vec{E}^2 + (1/\mu_0) \vec{B}^2) d^3 r = 0$

→ $\boxed{\sum_{\alpha} (Q_{\alpha}^E + \vec{v}_{\alpha} \cdot \vec{Q}_{\alpha}^S - \frac{1}{2} \vec{v}_{\alpha}^2 Q_{\alpha}^C) = 0}$

- conditions for the mass and the momentum satisfied
- additional terms in the energy equations

- Energy equations:

$$\begin{aligned}
\frac{1}{\gamma_e - 1} \frac{\partial P_e}{\partial t} &= -\frac{1}{\gamma_e - 1} \vec{\nabla} \cdot (P_e \vec{v}_e) - P_e \vec{\nabla} \cdot \vec{v}_e + \mathcal{L}_e^r \\
&+ \frac{\gamma_n}{\gamma_n - 1} \frac{m_e}{m_e + m_i} \frac{k_B T_n}{m_n} \iota \rho_n - \frac{\gamma_e}{\gamma_e - 1} \frac{k_B T_e}{m_e} \xi \rho_i \rho_e \\
&+ \frac{m_i}{m_i + m_e} \nu_{ie} \rho_i (\vec{v}_i - \vec{v}_e)^2 + \frac{m_n}{m_n + m_e} \nu_{ne} \rho_n (\vec{v}_n - \vec{v}_e)^2 \\
&+ \frac{m_d}{m_d + m_e} \nu_{de} \rho_d (\vec{v}_d - \vec{v}_e)^2 - 2 \frac{\rho_e \nu_{ei}}{m_e + m_i} \left(\frac{k_B T_e}{\gamma_e - 1} - \frac{k_B T_i}{\gamma_i - 1} \right)^2 \\
&- 2 \frac{\rho_e \nu_{en}}{m_e + m_n} \left(\frac{k_B T_e}{\gamma_e - 1} - \frac{k_B T_n}{\gamma_n - 1} \right)^2 - 2 \frac{\rho_e \nu_{ed}}{m_e + m_d} \left(\frac{k_B T_e}{\gamma_e - 1} - \frac{k_B T_d}{\gamma_d - 1} \right)^2 \\
\frac{1}{\gamma_i - 1} \frac{\partial P_i}{\partial t} &= -\frac{1}{\gamma_i - 1} \vec{\nabla} \cdot (P_i \vec{v}_i) - P_i \vec{\nabla} \cdot \vec{v}_i + \mathcal{L}_i^r + \frac{\gamma_n}{\gamma_n - 1} \frac{m_i}{m_e + m_i} \frac{k_B T_n}{m_n} \iota \rho_n \\
&- \frac{\gamma_i}{\gamma_i - 1} \frac{k_B T_i}{m_i} \xi \rho_i \rho_e + \frac{m_i}{2(m_n + m_i)} (\iota \rho_n + \xi \rho_i \rho_e) (\vec{v}_i - \vec{v}_n)^2 \\
&+ \frac{m_e}{m_e + m_i} \nu_{ei} \rho_e (\vec{v}_e - \vec{v}_i)^2 + \frac{m_n}{m_n + m_i} \nu_{ni} \rho_n (\vec{v}_n - \vec{v}_i)^2 \\
&+ \frac{m_d}{m_d + m_i} \nu_{di} \rho_d (\vec{v}_d - \vec{v}_i)^2 - 2 \frac{\rho_i \nu_{ie}}{m_i + m_e} \left(\frac{k_B T_i}{\gamma_i - 1} - \frac{k_B T_e}{\gamma_e - 1} \right)^2 \\
&- 2 \frac{\rho_i \nu_{in}}{m_i + m_n} \left(\frac{k_B T_i}{\gamma_i - 1} - \frac{k_B T_n}{\gamma_n - 1} \right)^2 - 2 \frac{\rho_i \nu_{id}}{m_i + m_d} \left(\frac{k_B T_i}{\gamma_i - 1} - \frac{k_B T_d}{\gamma_d - 1} \right)^2 \\
\frac{1}{\gamma_n - 1} \frac{\partial P_n}{\partial t} &= -\frac{1}{\gamma_n - 1} \vec{\nabla} \cdot (P_n \vec{v}_n) - P_n \vec{\nabla} \cdot \vec{v}_n + \mathcal{L}_n^r - \frac{\gamma_n}{\gamma_n - 1} \frac{k_B T_n}{m_n} \iota \rho_n \\
&+ \left(\frac{\gamma_e}{\gamma_e - 1} \frac{k_B T_e}{m_e} + \frac{\gamma_i}{\gamma_i - 1} \frac{k_B T_i}{m_e} \right) \xi \rho_i \rho_e + \frac{m_n}{2(m_i + m_n)} (\iota \rho_n + \xi \rho_i \rho_e) (\vec{v}_i - \vec{v}_n)^2 \\
&+ \frac{m_e}{m_e + m_n} \nu_{en} \rho_e (\vec{v}_e - \vec{v}_n)^2 + \frac{m_i}{m_i + m_n} \nu_{in} \rho_i (\vec{v}_i - \vec{v}_n)^2 \\
&+ \frac{m_d}{m_d + m_n} \nu_{dn} \rho_n (\vec{v}_d - \vec{v}_n)^2 - 2 \frac{\rho_n \nu_{ne}}{m_n + m_e} \left(\frac{k_B T_n}{\gamma_n - 1} - \frac{k_B T_e}{\gamma_e - 1} \right)^2 \\
&- 2 \frac{\rho_n \nu_{ni}}{m_n + m_i} \left(\frac{k_B T_n}{\gamma_n - 1} - \frac{k_B T_i}{\gamma_i - 1} \right)^2 - 2 \frac{\rho_n \nu_{nd}}{m_n + m_d} \left(\frac{k_B T_n}{\gamma_n - 1} - \frac{k_B T_d}{\gamma_d - 1} \right)^2 \\
\frac{1}{\gamma_d - 1} \frac{\partial P_d}{\partial t} &= -\frac{1}{\gamma_d - 1} \vec{\nabla} \cdot (P_d \vec{v}_d) - P_d \vec{\nabla} \cdot \vec{v}_d + \mathcal{L}_d^r \\
&+ \frac{m_e}{m_e + m_d} \nu_{ed} \rho_e (\vec{v}_e - \vec{v}_d)^2 + \frac{m_i}{m_i + m_d} \nu_{id} \rho_i (\vec{v}_i - \vec{v}_d)^2 \\
&+ \frac{m_n}{m_n + m_d} \nu_{nd} \rho_n (\vec{v}_n - \vec{v}_d)^2 - 2 \frac{\rho_d \nu_{de}}{m_d + m_e} \left(\frac{k_B T_d}{\gamma_d - 1} - \frac{k_B T_e}{\gamma_e - 1} \right)^2 \\
&- 2 \frac{\rho_d \nu_{di}}{m_d + m_i} \left(\frac{k_B T_d}{\gamma_d - 1} - \frac{k_B T_i}{\gamma_i - 1} \right)^2 - 2 \frac{\rho_d \nu_{dn}}{m_d + m_n} \left(\frac{k_B T_d}{\gamma_d - 1} - \frac{k_B T_n}{\gamma_n - 1} \right)^2
\end{aligned}$$

- \mathcal{L}^r radiative gains, losses